

Conceptos básicos Astronomía de Posición

18/08/22

- Sistemas de coordenadas celestes
- El paralaje estelar y el movimiento propio
- "The GAIA Celestial Reference Frame"



Sistemas de coordenadas celestes (Horizontales y ec. horarias)

Diagram illustrating the transformation of celestial coordinates:

$$x = \cos \theta \cos \phi$$

$$y = \cos \theta \sin \phi$$

$$z = \sin \theta$$

$$x' = \cos \theta' \cos \phi'$$

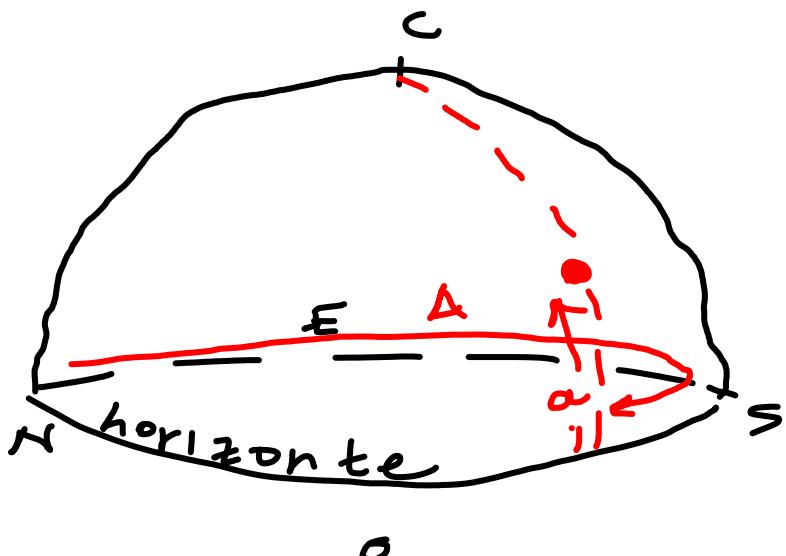
$$y' = \cos \theta' \sin \phi'$$

$$z' = \sin \theta'$$

$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \phi & \sin \phi \\ 0 & -\sin \phi & \cos \phi \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

Rotación @ x en sentido horario

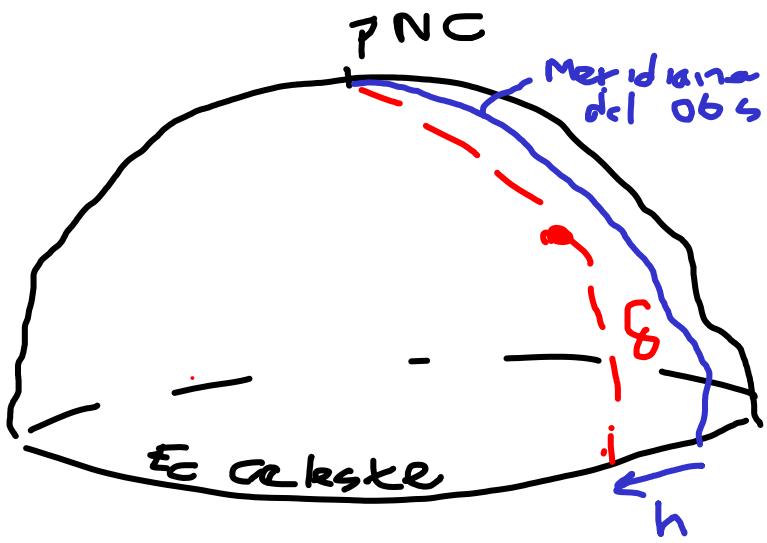
Coordenadas horizontales



$$0^\circ \leq \Delta \leq 360^\circ$$

$$-90^\circ \leq \alpha \leq 90^\circ$$

Coordenadas ecuatoriales horarias



$$0^\circ \leq h \leq 24^\circ$$

$$-90^\circ \leq \delta \leq 90^\circ$$

De horizontales a ecuatoriales :

$$\psi = 90^\circ - A , \quad \theta = a ,$$

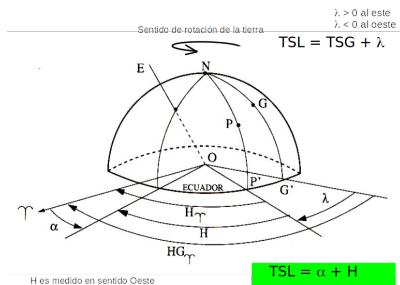
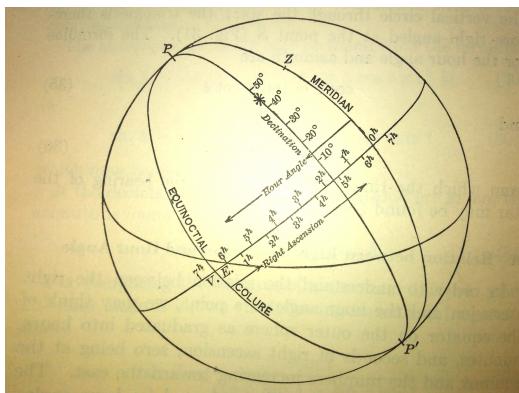
$$\psi' = 90^\circ - h , \quad \theta' = \delta , \quad \chi = 90^\circ - \phi .$$

$$\sin h \cos \delta = \sin A \cos a ,$$

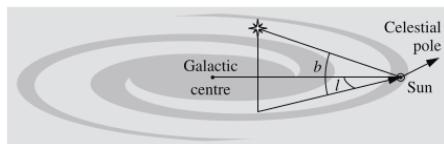
$$\cos h \cos \delta = \cos A \cos a \sin \phi + \sin a \cos \phi ,$$

$$\sin \delta = - \cos A \cos a \cos \phi + \sin a \sin \phi$$

Coordenadas Ecuatoriales Absolutas



Coordenadas Galácticas



$$\begin{aligned} \sin(l_N - l) \cos b &= \cos \delta \sin(\alpha - \alpha_P), \\ \cos(l_N - l) \cos b &= -\cos \delta \sin \delta_P \cos(\alpha - \alpha_P) \\ &\quad + \sin \delta \cos \delta_P, \\ \sin b &= \cos \delta \cos \delta_P \cos(\alpha - \alpha_P) \\ &\quad + \sin \delta \sin \delta_P, \end{aligned}$$

where the direction of the Galactic north pole is $\alpha_P = 12^{\text{h}} 51.4 \text{ min}$, $\delta_P = 27^{\circ} 08'$, and the galactic longitude of the celestial pole, $l_N = 123.0^\circ$.

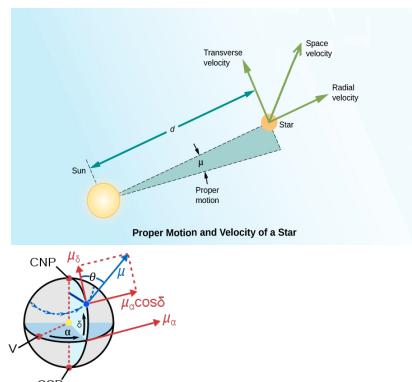
El movimiento propio

Desplazamiento angular aparente durante el año debido a su movimiento en el espacio respecto al sol.

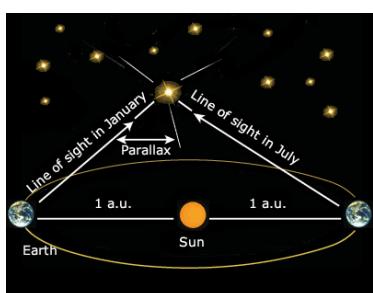
$$v_{\text{space}} = \sqrt{v_{\text{radial}}^2 + (4.74\mu \cdot d)^2}$$

La magnitud del movimiento propio:

$$\mu^2 = \mu_\delta^2 + \mu_\alpha^2 \cdot \cos^2 \delta.$$



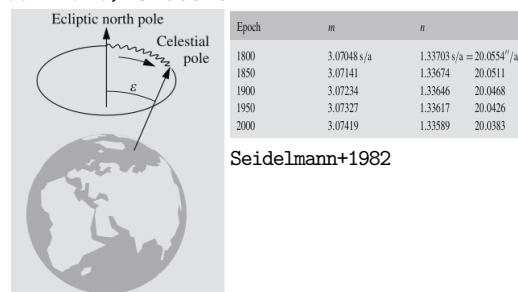
El paralaje estelar



La búsqueda de un sistema de referencia inercial universal

1991 IAU "Rotation Free". Coordenadas precisas de objetos extragalácticos
 Origen : Baricentro del sistema solar con ejes fijos con respecto a objetos extragalácticos.

ICRF (International Celestial Reference Frame) J2000.0



ICRF3 datasets

- ICRF3 includes solutions at **three different radio bands**: X/S, K and Ka/X-bands



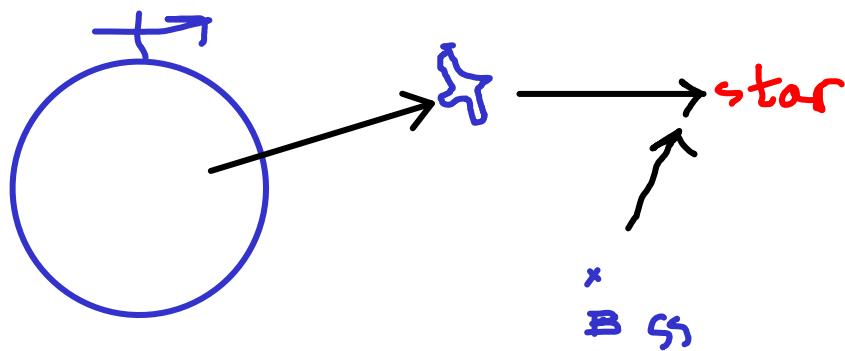
Band	Frequency (GHz)	Nb of obs. (millions)	Fraction of observations (%)				Data span	
			IVS	VLBA	Ht-Ho	DSN		
X/S	8.4 / 2.3	13.2	74	26			1979-2018	
K	24	0.5		99	1		2002-2018	
Ka/X	32 / 8.4	0.07				87	13	2005-2018

GFZ
 German Center
 for
 Geodetic
 Research

HELMHOLTZ
 RESEARCH FOR GRAND CHALLENGES

The GAIA Celestial Reference Frame

IAU 2000 adopta "Post Newtonian Parametrized" PPN version de la RG
 Los ejes se alinean con ICRF. Gaia toma como referencia el baricentro del SS



Modelo astrométrico

Permite obtener el movimiento propio para cualquier fuente en un instante t en términos de variables auxiliares bien conocidas.

The astrometric core solution for the Gaia mission

Overview of models, algorithms, and software implementation

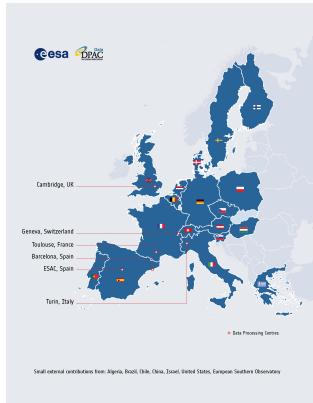
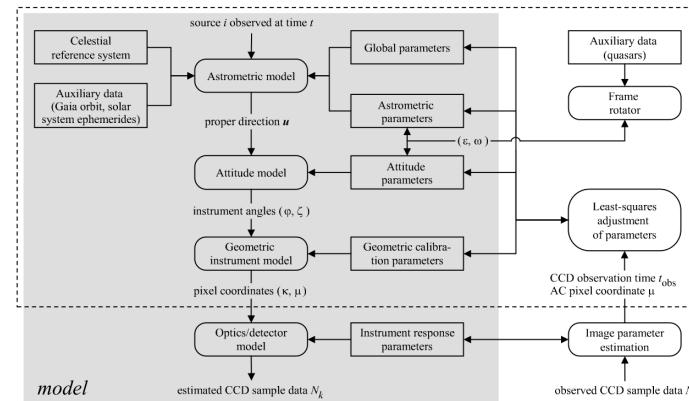
L. Lindegren¹, U. Lammers², D. Hobbs¹, W. O'Mullane², U. Bastian³, and J. Hernández²

¹ Lund Observatory, Lund University, Box 43, 22100 Lund, Sweden
e-mail: [Lennart.Lindegren;David.Hobbs]@astro.lu.se

² European Space Agency (ESA), European Space Astronomy Centre (ESAC), PO Box (Apdo. de Correos) 78, 28691 Villanueva de la Cañada, Madrid, Spain
e-mail: [Uwe.Lammers;William.O'Mullane;Jose.Hernandez]@sciops.esa.int

³ Astronomisches Rechen-Institut, Zentrum für Astronomie der Universität Heidelberg, Mönchhofstr. 12–14, 69120 Heidelberg, Germany
e-mail: bastian@ari.uni-heidelberg.de

$$\min_{s, n} \|f^{\text{obs}} - f^{\text{calc}}(s, n)\|_M,$$



"unknows" 5e8
solution uses 10e11 individual obs (70TB)
DPAC responsable de general el catálogo

